

## *Fast bin picking at Vision++*

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A new full operational installation is realized!

Vision++ is proud to present you a new Random Bin Picking showcase in which a robot equipped with a double gripper sorts randomly organized graphite.

This installation was realized in cooperation with Plakoni and Hupico for the GRaB project. In this project Vision++ has developed a Generic Random Bin Picking platform that enables a swift integration between our industrial vision applications and a wide variety of robots. With this, we can offer a faster, more reliable and robust solution to your bin picking problems.

The demonstration video highlights the accuracy and speed of the system. Keep an eye on our website for more demo's!

More information? [Contact us](#) on or visit the [GRaB project website](#).

This demonstration was realized in the GRaB project, supported by the agency for [Innovation by Science and Technology](#).